SPECIFICATIONS **HX130**LCR

Tior 4 Final Engine

Net Power SAE J1349 / 71 HP (53 kW) at 2,200 rpm **Bucket Range** 0.30 - 0.59 m³ (0.39 - 0.77 yd³) **Standard Bucket** 0.40 m³ (0.52 yd³) Operating Weight 13,495 kg (29,750 lb)

ENGINE		
Maker / Model	Perkins 854F	HVUNDAI
Туре	Water cooled, 4 cycle Diesel, 4-cylinders in line, direct injection, turbocharged charger and air cooled.	
Rated J1995 (gross)	73.6 HP (55 kW) / 2,200 rpm	
flywheel SAE J1349 (net)	71 HP (53 kW) / 2,200 rpm	
Max. torque	43.2 kgf.m (313 lbf.ft) / 1,200 rpm	And the same of th
Bore X stroke	99 x 110 mm (3.89" x 4.33")	HX130tes
Piston displacement	3,400 cc (207 in³)	
Batteries	2 x 12 V x 100 Ah	
Starting motor	24 V - 4.5 kW	
Alternator	24 V - 65 Amp	
HYDRAULIC SYSTEM		いいまり 意味 カンドン はいいかく おりかけ
MAIN PUMP		OPERATING WEIGHT (APPROXIMATE)
	Variable displacement tandom axis picton	OF ENATING WEIGHT (AFTROXIMATE)

Operating weight, including 4,300 mm (14' 1") boom, 2,810 mm (9' 3") arm, SAE heaped 0.40 m^3 (0.52 yd^3) bucket, lubricant, coolant, full fuel tank, full hydraulic tank, and all standard equipment.

OPERATING WEIGHT

Shoes	noes Operating weight						
Туре	Width mm (in)	kg (lb)	kgf/cm² (psi)				
	600 (24")	HX130LCR	13,495 (29,750)	0.37 (5.26)			
Triple		HX130LCR (Dozer type)	14,195 (31,290)	0.39 (5.54)			
grouser	700 (20")	HX130LCR	13,655 (30,100)	0.32 (4.55)			
	700 (28")	HX130LCR (Dozer type)	14,355 (31,650)	0.34 (4.83)			

SWING SYSTEM	
Swing motor	Fixed displacement axial piston motor
Swing reduction	Planetary gear reduction
Swing bearing lubrication	Grease-bathed
Swing brake	Multi wet disc
Swing speed	12.6 rpm

SERVICE REFILL CAPACITIES					
Re-filling	liter	US gal			
Fuel tank	240	63.4			
Engine coolant	20	5.3			
Engine oil	8.0	2.1			
Swing device	2.5	0.7			
Final drive (each)	2.3	0.6			
Hydraulic system (including tank)	160	42.3			
Hydraulic tank	96	25.4			

UNDERCARRIAGE

The X-leg type center frame is integrally welded with reinforced box-section track frames. The undercarriage includes lubricated rollers, idlers, track adjusters with shock absorbing springs and sprockets, and a track chain with double or triple grouser shoes.

Center frame	X - leg type
Track frame	Pentagonal box type
No. of shoes on each side	43 EA
No. of carrier roller on each side	1 EA
No. of track roller on each side	6 EA
No. of rail guard on each side	1 EA

Max. flow 2 x 126 \(\textit{\textit{\textit{Mmin}}} \) (33.3 \(\text{US gpm} \) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 \(\text{kgf/cm}^2 \) (4,690 \(\text{psi} \)) Power boost (boom, am, bucket) 330 \(\text{kgf/cm}^2 \) (4,690 \(\text{psi} \)) Swing circuit 285 \(\text{kgf/cm}^2 \) (5,120 \(\text{psi} \)) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 \(\text{mm} \) (3.74" x 40") Arm: 1-110 x 1,070 \(\text{mm} \) (3.74" x 40") Bucket: 1-100 x 855 \(\text{mm} \) (3.9" x 33.7") Blade: 2-100 x 240 \(\text{mm} \) (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 \(\text{kgf} \) (25,100 \(\text{lpf} \)) Gradeability 35° (70%) Parking brake Multi wet disc	Maker / Model	Perkins 854F
flywheel horse power horse power horse power horse power horse power horse power was not power to horse power horse power horse power was not power to horse power	Type	4-cylinders in line, direct injection,
Norse power J1349 (net)	31999 (gloss)	73.6 HP (55 kW) / 2,200 rpm
Bore X stroke 99 x 110 mm (3.89" x 4.33") Piston displacement 3,400 cc (207 in³) Batteries 2 x 12 V x 100 Ah Starting motor 24 V - 4.5 kW Alternator 24 V - 65 Amp HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pisto pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (5,70 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	140.40 (.)	71 HP (53 kW) / 2,200 rpm
Piston displacement 3,400 cc (207 in³) Batteries 2 x 12 V x 100 Ah Starting motor 24 V - 4.5 kW Alternator 24 V - 65 Amp HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pisto pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (5,120 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Blade: 2-100 x 240 mm (3.9" x 93.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake	Max. torque	43.2 kgf.m (313 lbf.ft) / 1,200 rpm
Batteries 2 x 12 V x 100 Ah Starting motor 24 V - 4.5 kW Alternator 24 V - 65 Amp HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pisto pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Swing circuit 285 kgf/cm² (4,050 psi) Power boost (boom, am, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS No. of cylinder Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max: travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	Bore X stroke	99 x 110 mm (3.89" x 4.33")
Starting motor Alternator Alternator Alternator Alternator Alternator 24 V - 65 Amp HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pisto pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	Piston displacement	3,400 cc (207 in³)
Alternator HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pistor pumps Max. flow Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 330 kgf/cm² (4,690 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (5,120 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability Parking brake Multi wet disc	Batteries	2 x 12 V x 100 Ah
HYDRAULIC SYSTEM MAIN PUMP Type Variable displacement tandem axis pistor pumps Max. flow 2 x 126 \(\frac{U}\text{rmin} \) (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Blade: 2-100 x 240 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive motor Reduction system Planetary reduction gear Max. drawbar pull Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability Parking brake Multi wet disc	Starting motor	24 V - 4.5 kW
MAIN PUMP Type Variable displacement tandem axis pistor pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS No. of cylinder bore X stroke Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 9arking brake Multi wet disc	Alternator	24 V - 65 Amp
Type Variable displacement tandem axis pistor pumps Max. flow 2 x 126 l/min (33.3 US gpm) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS No. of cylinder Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	HYDRAULIC SYSTEM	
Max. flow 2 x 126 \(\textit{\textit{\textit{Mmin}}} \) (33.3 \(\text{US gpm} \) Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Travel Two speed axial pistons motor with brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 \(\text{kgf/cm}^2 \) (4,690 \(\text{psi} \)) Power boost (boom, am, bucket) 330 \(\text{kgf/cm}^2 \) (4,690 \(\text{psi} \)) Swing circuit 285 \(\text{kgf/cm}^2 \) (5,120 \(\text{psi} \)) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 \(\text{mm} \) (3.74" x 40") Arm: 1-110 x 1,070 \(\text{mm} \) (3.74" x 40") Bucket: 1-100 x 855 \(\text{mm} \) (3.9" x 33.7") Blade: 2-100 x 240 \(\text{mm} \) (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 \(\text{kgf} \) (25,100 \(\text{lpf} \)) Gradeability 35° (70%) Parking brake Multi wet disc	MAIN PUMP	
Sub-pump for pilot circuit Gear pump CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Travel Travel Travel Setting Axial piston motor with automatic brake valve and parking brake Swing Axial piston motor with automatic brake valve and parking brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 340 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (570 psi) Filot circuit 40 kgf/cm² (570 psi) Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Multi wet disc	Туре	Variable displacement tandem axis pisto pumps
CROSS-SENSING AND FUEL-SAVING PUMP SYSTEM HYDRAULIC MOTORS Travel Travel Travel Travel Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability 35° (70%) Parking brake	Max. flow	2 x 126 l/min (33.3 US gpm)
Travel Axial piston motor with brake valve and parking brake Swing Axial piston motor with automatic brake Travel	Sub-pump for pilot circuit	Gear pump
Travel Axial piston motor with brake valve and parking brake Swing Axial piston motor with automatic brake Travel	CROSS-SENSING AND FUEL-S	AVING PUMP SYSTEM
brake valve and parking brake Swing Axial piston motor with automatic brake RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Drive method Fully hydrostatic type Drive motor Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc		
RELIEF VALVE SETTING Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, am, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc	Travel	
Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc	Swing	Axial piston motor with automatic brake
Implement circuits 330 kgf/cm² (4,690 psi) Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc	RELIEF VALVE SETTING	
Travel 330 kgf/cm² (4,690 psi) Power boost (boom, arm, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc		330 kaf/cm² (4.690 psi)
Power boost (boom, am, bucket) 360 kgf/cm² (5,120 psi) Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc	<u>'</u>	
Swing circuit 285 kgf/cm² (4,050 psi) Pilot circuit 40 kgf/cm² (570 psi) Service valve Installed HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability 35° (70%) Parking brake Multi wet disc	Power boost (boom, arm, bucket)	
Service valve HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc		
Service valve HYDRAULIC CYLINDERS Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Multi wet disc	Pilot circuit	40 kgf/cm² (570 psi)
Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method	Service valve	
Boom: 2-95 x 1,015 mm (3.74" x 40") Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method	LIVERALILIC CVI INDERC	
No. of cylinder bore X stroke Arm: 1-110 x 1,070 mm (4.3" x 42.1") Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	HYDRAULIC CYLINDERS	Decree 2.05 v. 1.015 mans /2.74" v. 40"\
bore X stroke Bucket: 1-100 x 855 mm (3.9" x 33.7") Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	N. 6 1: 1	
Blade: 2-100 x 240 mm (3.9" x 9.4") DRIVES & BRAKES Drive method Drive motor Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) Gradeability Parking brake Blade: 2-100 x 240 mm (3.9" x 9.4") Fully hydrostatic type Axial piston motor, in-shoe design Planetary reduction gear 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Multi wet disc		
DRIVES & BRAKES Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	DOIE A STIONE	
Drive method Fully hydrostatic type Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc		blade. 2-100 x 240 Hill (5.9 x 9.4)
Drive motor Axial piston motor, in-shoe design Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	DRIVES & BRAKES	
Reduction system Planetary reduction gear Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	Drive method	Fully hydrostatic type
Max. drawbar pull 11,400 kgf (25,100 lbf) Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	Drive motor	Axial piston motor, in-shoe design
Max. travel speed (high / low) 5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph) Gradeability 35° (70%) Parking brake Multi wet disc	Reduction system	Planetary reduction gear
Gradeability 35° (70%) Parking brake Multi wet disc	Max. drawbar pull	11,400 kgf (25,100 lbf)
Parking brake Multi wet disc	Max. travel speed (high / low)	5.5 km/hr (3.4 mph) / 3.3 km/hr (2.1 mph)
<u> </u>	Gradeability	35° (70%)
CONTROL	Parking brake	Multi wet disc
	CONTROL	

Pilot pressure operated joysticks and pedals with detachable lever provide almost

Two joysticks with one safety lever

(LH): Swing and arm (RH): Boom and bucket (ISO)

Two levers with pedals

Electric, dial type

effortless and fatigueless operation.

Pilot control

Engine throttle

Traveling and steering

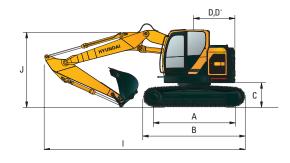
SPECIFICATIONS **HX130**LCR

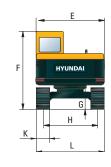
Tier 4 Final Engine

HX130LCR DIMENSIONS Unit: mm (ft·in)

4.3 m (14' 1") boom and 1.96 m (6' 5"), 2.26 m (7' 5"), 2.81 m (9' 3") arm

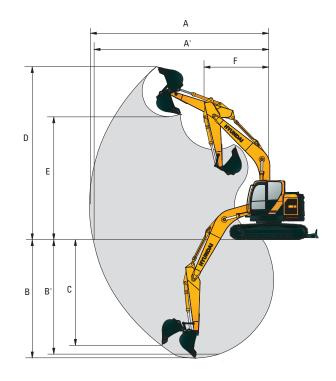
Α	Tumbler distance	2,780 (9' 1")
В	Overall length of crawler	3,490 (11' 5")
C	Ground clearance of counterweight	900 (2′ 11″)
D	Tail swing radius	1,500 (4′ 11″)
D'	Rear-end length	1,500 (4′ 11″)
Е	Overall width of upperstructure	2,500 (8′ 2″)
F	Overall height of cab	2,900 (9′ 6″)
G	Min. ground clearance	440 (1′ 5″)
Н	Track gauge	1,990 (6′ 6″)





	Boom length	4,300 (14' 1")			
	Arm length	1,960 (6′ 5″)	2,260 (7′ 5″)	2,810 (9′ 3″)	
ı	Overall length	6,820 (22′ 5″)	6,860 (22′ 6″)	6,810 (22′ 2″)	
J	Overall height of boom	2,530 (8′ 4″)	2,750 (9′ 0″)	3,080 (10′ 1″)	
		500	600	700	
K	Track shoe width	(20")	(24")	(28")	
L	Overall width	2,500 (8′ 2″)	2,600 (8′ 6″)	2,700 (8′ 10″)	

HX130LCR WOR	HX130LCR WORKING RANGE						
Boom length			4,300 (14′ 1″)				
Arm length		1,960 (6′ 5″)	2,260 (7′ 5″)	2,810 (9′ 3″)			
A Max. digging re	ach	7,410 (24′ 3″)	7,690 (25′ 3″)	8,220 (27′ 0″)			
A' Max. digging read	ch on ground	7,250 (23′ 10″)	7,540 (24′ 10″)	8,080 (26′ 6″)			
B Max. digging do	epth	4,720 (15′ 6″)	5,020 (16' 6")	5,570 (18' 4")			
B' Max. digging de	epth (8' level)	4,460 (14′ 8″)	4,790 (15′ 90″)	5,380 (17′ 8″)			
C Max. vertical wall	digging depth	3,960 (13′ 0″)	4,290 (14' 1")	4,830 (15′ 11″)			
D Max. digging he	eight	7,920 (26′ 0″)	8,110 (26′ 6″)	8,480 (27′ 10″)			
E Max. dumping	height	5,620 (18′ 5″)	5,800 (19' 0")	6,170 (20′ 3″)			
F Min. swing radi	us	2,310 (7′ 6″)	2,340 (7′ 8″)	2,470 (8′ 2″)			



ATTACHMENT

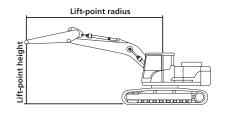
Booms and arms are welded, and feature a low stress, full-box section design. 4.6 m (15' 1"), 4.9 m (16' 1") boom and 1.9 m (6' 3"), 2.1 m (6' 11"), 2.5 m (8' 2"), 3.0 m (9' 10") arms are available.

DIGGING FORCE							
A rm	Length	mm (ft.in)	1,960 (6′ 5″)	2,260 (7′ 5″)	2,810 (9′ 3″)		
Arm	Weight	kg (lb)	330 (730)	355 (780)	430 (950)		
	SAE	kgf	8,954 [9,768]	8,954 [9,768]	8,954 [9,768]		
Bucket		lbf	19,740 [21,534]	19,740 [21,534]	19,740 [21,534]		
digging force		kgf	10,369 [11,312]	10,369 [11,312]	10,369 [11,312]	[Power	
.0.00		lbf	22,860 [24,938]	22,860 [24,938]	22,860 [24,938]	Boost]	
	CAF	kgf	6,178 [6,739]	5,716 [6,236]	4,928 [5,376]		
Arm	SAE	lbf	13,619 [14,857]	12,602 [13,747]	10,865 [11,852]		
crowd force	ICO	kgf	6,443 [7,029]	5,943 [6,484]	5,093 [5,556]		
	ISO	lbf	14,204 [15,495]	13,103 [14,294]	12,228 [12,249]		

Note : Arm weight includes bucket cylinder, linkage, and $\operatorname{\mathsf{pin}}$

SPECIFICATIONS **HX130**LCR

Tier 4 Final Engine



Lifting Capacity

Boom: 4.3 m (14' 1") Arm: 2.81 m (9' 3")

Capacities based on North American Standard Configuration in accordance with ISO condition 2 standard.

Bucket: 0.40 m³ (0.52 yd³) SAE heaped

Rating over front

Shoe 500 mm (20") triple grouser CWT 2 350 kg (5 181 lb)

Rating over side or 360 degree

Shoe 5	00 m	nm (20") trip	ole grouser, C	VVI 2,350 Kg	(5,181 lb)					Rating ove	er side or 360) degree	
			Load radius								At max. reach		
Load po	nt	1.5 m	(4.9 ft)	3.0 m	(9.8 ft)	4.5 m ((14.8 ft)	6.0 m (19.7 ft)	Сар	acity	Reach	
(m / f	τ)	Ū		I				Ū		Į.		m (ft)	
6.0 m	kg					*2,460	*2,460			*1,760	*1,760	5.36	
(20 ft)	lb					*5,420	*5,420			*3,880	*3,880	(17.6)	
4.5 m	kg					*2,550	*2,550	*2,380	2,280	*1,600	*1,600	6.34	
(15 ft)	lb					*5,620	*5,620	*5,250	5,030	*3,530	*3,530	(20.8)	
3.0 m	kg			*3,820	*3,820	*3,210	*3,210	*2,980	2,230	*1,570	*1,570	6.86	
(10 ft)	lb			*8,420	*8,420	*7,080	*7,080	*6,570	4,920	*3,460	*3,460	(22.5)	
1.5 m	kg			*6,270	6,210	*4,150	3,310	*3,380	2,150	*1,650	*1,650	7.03	
(5 ft)	lb			*13,820	13,690	*9,150	7,300	*7,450	4,740	*3,640	*3,640	(23.1)	
Ground	kg			*7,830	5,830	*4,940	3,140	*3,740	2,080	*1,830	1,710	6.86	
Line	lb			*17,260	12,850	*10,890	6,920	*8,250	4,590	*4,030	3,770	(22.5)	
-1.5 m	kg	*4,170	*4,170	*8,140	5,720	*5,260	3,070	*3,830	2,050	*2,210	1,900	6.34	
(-5 ft)	lb	*9,190	*9,190	*17,950	12,610	*11,600	6,770	*8,440	4,520	*4,870	4,190	(20.8)	
-3.0 m	kg	*7,330	*7,330	*7,430	5,780	*4,880	3,090			*3,140	2,430	5.36	
(-10 ft)	lb	*16,160	*16,160	*16,380	12,740	*10,760	6,810			*6,920	5,360	(17.6)	

NOTES:

- 1. Lifting capacities are based on ISO 10567.
- 2. Lifting capacity of the HX Series does not exceed 75% of tipping load with the machine on firm, level ground or 87% of full hydraulic capacity.
- 3. The Lift-point is bucket pivot mounting pin on the arm (without bucket mass).
- 4. (*) indicates load limited by hydraulic capacity.

BUCKETS

All buckets are welded with high-strength steel.











SAE Heaped m³ (yd³)

0.30 (0.39)

0.40 (0.52)

0.45 (0.59)

0.50 (0.65)

0.59 (0.77)

Capacity Widt		dth		Recommendation mm (ft-in)			
m³ ((yd³)	mm	(in)	Weight		4,300 (14' 1") Boom	
SAE Heaped	CECE Heaped	Without Side Cutters	With Side Cutters	kg (lb)	1,960 (6′ 5″) Arm	2,260 (7′ 5″) Arm	2,810 (9′ 3″) Arm
0.30 (0.39)	0.27 (0.35)	610 (24.0)	720 (28.3)	360 (790)			
0.40 (0.52)	0.44 (0.58)	760 (29.9)	870 (34.3)	410 (900)	•	•	•
0.45 (0.59)	0.40 (0.52)	830 (32.7)	940 (37.0)	430 (950)	•	•	
0.50 (0.65)	0.45 (0.59)	900 (35.4)	1,010 (39.8)	450 (990)	•		A
0.59 (0.77)	0.52 (0.68)	1,020 (40.2)	1,130 (44.5)	490 (1,080)		A	_

Applicable for materials with density of 2,000 kgf/m3 (3,370 lbf/yd3) or less

Applicable for materials with density of 1,600 kgf/m3 (2,700 lbf/yd3) or less
 Applicable for materials with density of 1,100 kgf/m3 (1,850 lbf/yd3) or less

SPECIFICATIONS IX130LCR

Tier 4 Final Engine

ENGINE	STD	OPT
Perkins 854F Engine	•	
HYDRAULIC SYSTEM		
Intelligent Power Control (IPC)		
3-power mode, 2-work mode, user mode	•	
Variable power control Pump flow control	•	
Attachment mode flow control	•	
Engine auto idle	•	
Engine auto shutdown control	_	•
Electronic fan control	•	
CAB & INTERIOR		
ISO Standard cabin		
Rise-up type windshield wiper		
Radio/USB player	•	
Handsfree mobile phone system with USB		
12 volt power outlet (24 V DC to 12 V DC converter)	•	
Electric horn		
All-weather steel cab with 360° visibility	•	
Safety glass windows	•	
Sliding fold-in front window	•	
Sliding side window (LH)	•	
Lockable door	•	
Storage compartment & ashtray	•	
Transparent cabin roof-cover	•	
Sun visor	•	
Door and cab locks, one key	•	
Pilot-operated adjustable joystick	•	
Console box height adjust system	•	
Smart start with key fob		•
Cabin lights	•	
Cabin front window rain guard		•
Automatic climate control		
Air conditioner & heater		
Defroster Defroster	•	
Starting Aid (air grid heater) for cold weather	•	
Centralized monitoring		
8" LCD display		
Engine speed or trip meter/accelerator		
Engine coolant temperature gauge	•	
Max power	•	
Low speed/High speed		
Auto idle	•	
Overload	•	
Check engine	•	
Air cleaner clogging	•	
Indicators	•	
ECO gauges	•	
Fuel level gauge	•	
Hydraulic oil temperature gauge	•	
Warnings	•	
Communication error	•	
Low battery	•	
Clock	•	

CAB & INTERIOR	STD	OP.				
Seat						
Adjustable air suspension seat with heater	•					
Cabin FOPS/FOG (ISO/DIS 10262) Level 2						
FOPS (Falling Object Protective Structure)-ISO 3,449 Level 2		•				
FOG (Falling Object Guard)		•				
Cabin ROPS (ISO 12117-2)						
ROPS (Roll Over Protective Structure)	•					
SAFETY	STD	OP				
Battery master switch	•					
Rearview camera	•					
AAVM (All-Around View Monitoring)		•				
Four front working lights (2 boom mounted, 2 front frame mounted)	•					
Travel alarm	•					
Rear work lamp	•					
Beacon lamp LED						
Automatic swing brake	•					
Boom holding system	•					
Arm holding system	•					
Safety lock valve for boom cylinder with overload warning device						
Safety lock valve for arm cylinder		•				
		-				
Swing lock system Two outside rearriew mirror		•				
	•					
Wirenet guard		•				
OTHER						
Booms						
4.3 m, 14' 1"	•					
Arms						
1.96 m, 6' 5"		•				
2.26 m, 7' 5"		•				
2.81 m, 9′ 3″						
Removable clean-out dust net for cooler						
Removable reservoir tank						
Fuel pre-filter	•					
	•					
Self-diagnostics system	•					
Mobile		_				
Mobile						
Hi-mate (Remote Management System)	•	•				
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah)		•				
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min)		•				
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control	•	•				
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control	•	•				
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping	•	•				
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment	•	•				
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns)	•	•				
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 \$\mathcal{U} \text{rinn}) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system	•					
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg	•					
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 \$\mathcal{U} \text{min}) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg UNDERCARRIAGE	•					
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg	•					
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 ½/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg UNDERCARRIAGE Lower frame under cover (Normal) Track shoes	•					
Hi-mate (Remote Management System) Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 ½/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg UNDERCARRIAGE Lower frame under cover (Normal)	•					
Hi-mate (Remote Management System) Mobile Satellite Batteries (2 x 12 V x 100 Ah) Fuel filler pump (50 l/min) Double-acting piping kit (clamshell, etc.) with proportional control Rotating piping kit with proportional control Hyundai dual-lock quick coupler with piping Accumulator for lowering work equipment Pattern change valve (2 patterns) Fine swing control system Heavier counterweight 5,180 lbs/ 2,350 kg UNDERCARRIAGE Lower frame under cover (Normal) Track shoes Triple grousers shoes (500 mm, 20")	•					

- * Standard and optional equipment may vary. Contact your Hyundai dealer for more information. The machine may vary according to International standards.

 * The photos may include attachments and optional equipment that are not available in your area.

 * Materials and specifications are subject to change without advance notice.

 * All imperial measurements rounded off to the nearest pound or inch.

A HYUNDAI **CONSTRUCTION EQUIPMENT**

www.hceamericas.com 6100 Atlantic Blvd., Norcross, GA 30071 TEL (678) 823 7777 FAX (678) 823 7778

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